L Number	Hits	Search Text	DB	Time stamp
- Number	1116	("5900909").PN.	USPAT;	2004/05/10 13:46
	-	(	US-PGPUB	
_	12	5900909.URPN.	USPAT	2004/05/04 17:25
<u>-</u>	3061	348/\$.ccls. and (compar\$3 check\$3 verify\$3) with position	USPAT;	2004/05/07 14:53
			US-PGPUB	
1.	522	348/\$.ccls. and (compar\$3 check\$3 verify\$3) with position and sav\$3	USPAT;	2004/05/05 08:38
		,	US-PGPUB	
<u> </u>	3	348/\$.ccls. and (compar\$3 check\$3 verify\$3) with position with sav\$3	USPAT;	2004/05/05 11:59
			US-PGPUB	
<u> </u>	39	348/\$.ccls. and (compar\$3 check\$3 verify\$3) with camera adj position	USPAT;	2004/05/05 13:58
	-		US-PGPUB	
_	5	(compar\$3 check\$3 verify\$3) adj camera adj position	USPAT;	2004/05/05 12:03
			US-PGPUB	
-	3	(compar\$3 check\$3 verify\$3) adj camera adj orientation	USPAT;	2004/05/05 12:04
		· · ·	US-PGPUB	
<u>-</u>	10	348/\$.ccls. and (compar\$3 check\$3 verify\$3) adj acceleration	USPAT;	2004/05/05 13:54
			US-PGPUB	
<u>-</u>	2	348/\$.ccls. and save with camera adj position	USPAT;	2004/05/05 14:00
		<b>3.</b>	US-PGPUB	
-	8	348/\$.ccls. and save with camera with position	USPAT;	2004/05/05 14:04
	_	•	US-PGPUB	
1-	21	348/\$.ccls. and add with (position adj data)	USPAT;	2004/05/05 17:19
			US-PGPUB	
1 -	220	add with (position adj data)	USPAT;	2004/05/05 14:23
		, ,	US-PGPUB	
-	6	camera same add with (position adj data)	USPAT;	2004/05/05 14:27
		· · · · ·	US-PGPUB	
-	66	invalid with (position adj data)	USPAT;	2004/05/10 14:15
			US-PGPUB	
-	376	(vibration shake acceleration) with (position adj data)	USPAT;	2004/05/07 14:57
			US-PGPUB	
-	15	348/\$.ccls. and (vibration shake acceleration) with (position adj data)	USPAT;	2004/05/05 14:59
			US-PGPUB	
-	173	(348/208.99,208.1,208.2,208.3).CCLS.	USPAT;	2004/05/10 10:50
			US-PGPUB	
-	11	((348/208.99,208.1,208.2,208.3).CCLS.) and position adj data	USPAT;	2004/05/05 15:04
			US-PGPUB	
-	114	348/\$.ccls. and orientation adj sensor	USPAT;	2004/05/05 16:48
			US-PGPUB	
-	1	348/\$.ccls. and save with (position adj data)	USPAT;	2004/05/05 17:20
		90 X 10 10 1 1 X	US-PGPUB	
-	57	save with (position adj data)	USPAT;	2004/05/06 08:39
		240/0 1 1/ 02 1 102 (0.00) (4 1/ 1/ 1/ 1/	US-PGPUB	2004/05/07 15 02
-	96	348/\$.ccls. and (compar\$3 check\$3 verify\$3) with position adj data	USPAT;	2004/05/07 15:03
	1.1	(vibration above acceleration) and (somers adi necition adi data)	US-PGPUB	2004/05/07 15:02
1-	11	(vibration shake acceleration) and (camera adj position adj data)	USPAT; US-PGPUB	2004/05/07 16:02
	7	348/\$.ccls, and acceleration and (compar\$3 check\$3 verify\$3) with	US-PGPUB USPAT;	2004/05/07 15:07
]-	′	position adj data	US-PGPUB	2004/03/07 13:07
	1689	348/\$.ccls. and orientation with image	USPAT;	2004/05/07 15:08
-	1007	348/G.CCIS. and offendation with image	US-PGPUB	2004/03/07 13.08
_	7	348/\$.ccls. and orientation adj data with image adj data	USPAT;	2004/05/07 15:08
_	,	3-40/4.ccis, and orientation adjudate with image adjudate	US-PGPUB	2004/03/07 13.08
1.	268	348/\$.ccls. and orientation with image with data	USPAT;	2004/05/07 15:34
	200	2 10, 4.2220, with origination with mange with data	US-PGPUB	230 1103/01 13.34
	2	348/\$.ccls. and save with orientation with image	USPAT;	2004/05/07 15:35
	1		US-PGPUB	200 1100101 10.00
1.	155751	348/\$.ccls. and save with positionadj data with image with data	USPAT;	2004/05/07 15:37
		To	US-PGPUB	200 1103101 13.51
-	1	348/\$.ccls. and save with position adj data with image with data	USPAT;	2004/05/07 15:53
	_		US-PGPUB	
-	7	348/\$.ccls, and save with position with image with data	USPAT;	2004/05/07 15:39
		• • • • • • • • • • • • • • • • • • • •	US-PGPUB	
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		<b>→</b>		
-	2	save with position adj data with image with data	USPAT; US-PGPUB	2004/05/07 15:53
-	29	348/\$.ccls. and acceleration adj sensor and (orientation position) adj	USPAT; US-PGPUB	2004/05/10 08:38
-	36	348/\$.ccls. and acceleration with (above exceed) with (limit value)	USPAT; US-PGPUB	2004/05/10 08:39
-	10	348/\$.ccls. and acceleration with (above exceed) with (limit value) same	USPAT; US-PGPUB	2004/05/10 08:47
-	3	position 348/\$.ccls. and correct adj position adj data	USPAT;	2004/05/10 08:49
-	238	348/\$.ccls. and correct with position with data	US-PGPUB USPAT;	2004/05/10 10:16
-	26	348/\$.ccls, and correct with position with data and acceleration	US-PGPUB USPAT;	2004/05/10 09:35
-	14	("3772649"   "4480278"   "4774564"   "4908646"   "4937676"	US-PGPUB USPAT	2004/05/10 09:56
		"5267042"   "5335072"   "5410225"   "5493409"   "5506644"   "5596494"   "5604928"   "5614870"   "5732182").PN.		
-	26	348/\$.ccls. and correct with orientation with data	USPAT; US-PGPUB	2004/05/10 10:04
-	95	348/\$.ccls. and correct with position with data and (above exceed) with (limit value)	USPAT; US-PGPUB	2004/05/10 10:18
-	7	348/\$.ccls. and correct with position with data same (above exceed) with (limit value)	USPAT; US-PGPUB	2004/05/10 10:25
-	2	save adj camera adj position	USPAT; US-PGPUB	2004/05/10 10:26
-	46	save with camera with position	USPAT; US-PGPUB	2004/05/10 11:03
-	174	(348/208.99,208.1,208.2,208.3).CCLS.	USPAT; US-PGPUB	2004/05/10 10:50
]-	6	((348/208.99,208.1,208.2,208.3).CCLS.) and acceleration and camera adj position	USPAT; US-PGPUB	2004/05/10 10:51
-	1048	correct with camera with position	USPAT; US-PGPUB	2004/05/10 11:08
-	1	согтесt adj camera adj position adj data	USPAT; US-PGPUB	2004/05/10 10:59
-	2	save with camera with orientation	USPAT; US-PGPUB	2004/05/10 11:04
-	148	correct with camera with orientation	USPAT; US-PGPUB	2004/05/10 11:04
-	1	correct with camera with orientation adj data	USPAT; US-PGPUB	2004/05/10 11:04
-	71	correct with camera with position and acceleration	USPAT; US-PGPUB	2004/05/10 11:09
-	5	positional adj data with (accurate correct verif\$3) same acceleration	USPAT; US-PGPUB	2004/05/10 11:49
-	250	positional adj data with (accurate correct verif\$3)	USPAT; US-PGPUB	2004/05/10 11:25
-	31	save with image with position with data	USPAT; US-PGPUB	2004/05/10 13:47